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Solution to Linear Algebra Hoffman & Kunze Chapter 1.3 Exercise 1.3.8. Solution: (a) In this case the system of equations is

$$\begin{aligned} 0 \cdot x_1 + 0 \cdot x_2 &= 0 \end{aligned}$$

~~Solve general linear equations with 2×2 matrix ...~~

Consider the system: $a \cdot x_1 + b \cdot x_2 = u$ $c \cdot x_1 + d \cdot x_2 = v$ If $ad - bc \neq 0$, then we can solve for x_1 and x_2 explicitly as $x_1 = \frac{du - bv}{ad - bc}$ $x_2 = \frac{av - cu}{ad - bc}$. Thus there's a unique solution for all (u, v) and in particular when $(u, v) = (0, 0)$. (c) Assume WOLOG that $a \neq 0$. Then $ad - bc = 0 \Rightarrow d = \frac{bc}{a}$.

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Exercise 2: Let F be the field of complex numbers. Are the following two systems of linear equations equivalent? If so, express each equation in each system as a linear combination of the equations in the other system. $x_1 - x_2 = 0$ $3x_1 + x_2 = 0$ $2x_1 + x_2 = 0$ $x_1 + x_2 = 0$ Solution: Yes the two systems are equivalent.

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Let $v_1 = (1, 0, 0)$, $v_2 = (0, 1, 0)$ and $v_3 = (1, 1, 0)$. Then $v_1 + v_2 - v_3 = (0, 0, 0)$ so they are linearly dependent. We know v_1 and v_2 are linearly independent as they are two of the standard basis vectors (see Example 13, page 41). Suppose $a v_1 + b v_3 = 0$. Then $(a + b, b, 0) = (0, 0, 0)$.

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Kenneth M Hoffman, Ray Kunze. This introduction to linear algebra features intuitive introductions and examples to motivate important ideas and to illustrate the use of results of theorems. Linear Equations; Vector Spaces; Linear Transformations; Polynomials; Determinants; Elementary canonical Forms; Rational and Jordan Forms; Inner Product Spaces; Operators on Inner Product Spaces; Bilinear Forms For all readers interested in linear algebra.

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If $T(A) = AB \neq BA$ verify that T is a linear transformation from V into V . Solution: $T(cA_1 + A_2) = (cA_1 + A_2)B \neq B(cA_1 + A_2) = cA_1 B + A_2 B \neq cBA_1 \neq BA_2 = c(A_1 B \neq BA_1) + (A_2 B \neq BA_2) = cT(A_1) + T(A_2)$. Section 3.2: The Algebra of Linear Transformations 55

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Solution: If A is not similar to a triangular matrix then the minimum polynomial of A must be of the form $(x^2 + ax + b)$ where $x^2 + ax + b$ has no real roots. The roots of $x^2 + ax + b$ are then two non-real complex conjugates z and \bar{z} .

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